



On the Controllability of a Floating Offshore Wind Turbine



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Abstract

- An analytical method for assessing the controllability of floating offshore wind turbines (FOWTs) is presented.
- Linear control theory principles are applied to linearized FOWT models to establish quantifiable metrics to determine differences in turbine models from a controls perspective.
- A simplified point-mass model to demonstrate the idea of control energy is introduced
- The DTU 10MW wind turbine on floating semi-submersible platforms is used to demonstrate these analysis methods within the FOWT space

Theory

The Controllability Gramian:

$$W_c(t) = \int_0^t e^{A(t-\tau)} B B^T e^{A^T(t-\tau)} d\tau$$

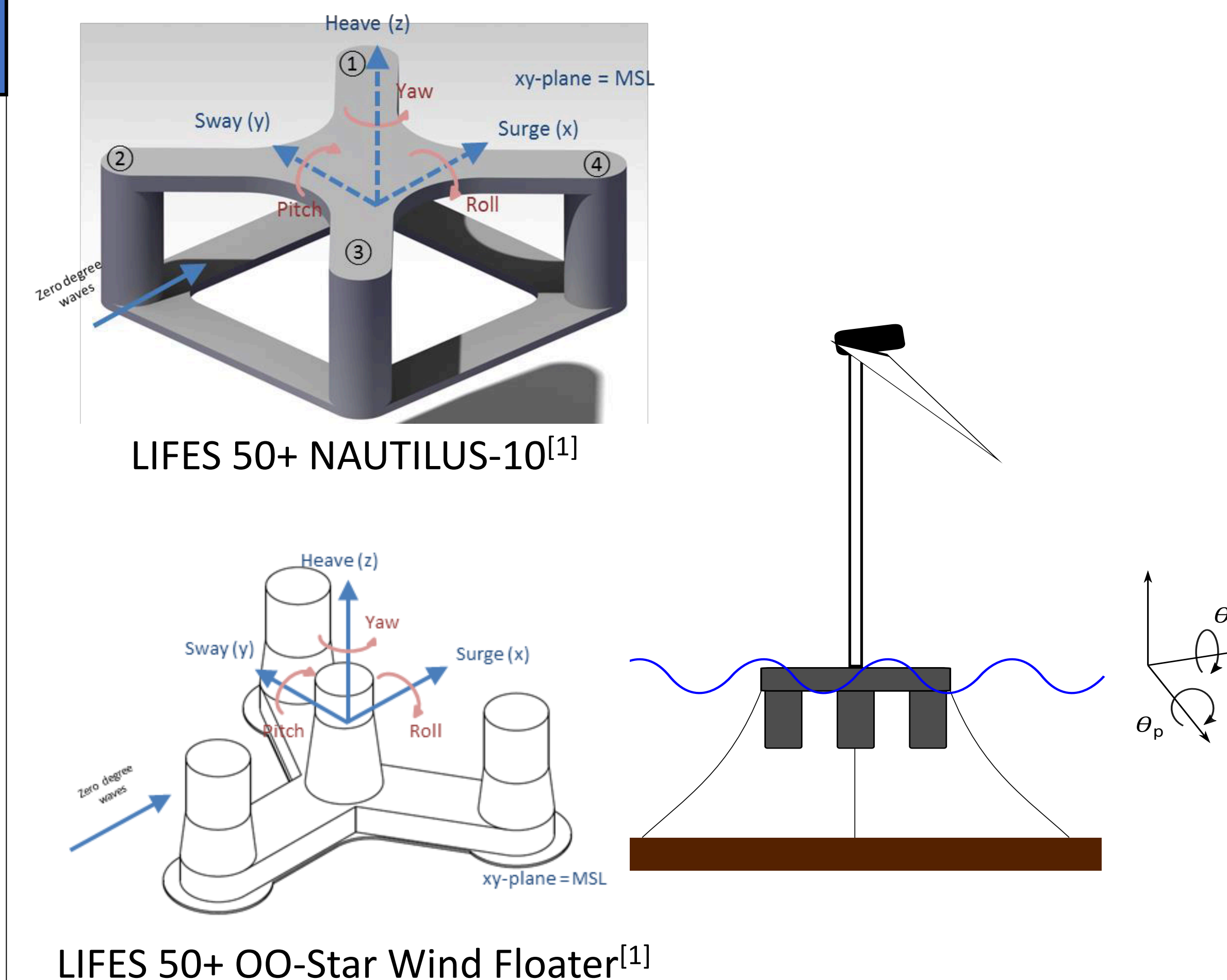
Energy to reach a desired state:

$$E_{x_{des},min}(t) = [e^{At_1} x_0 - x_{des}]^T W_c^{-1} [e^{At_1} x_0 - x_{des}]$$

Singular Value Decomposition:

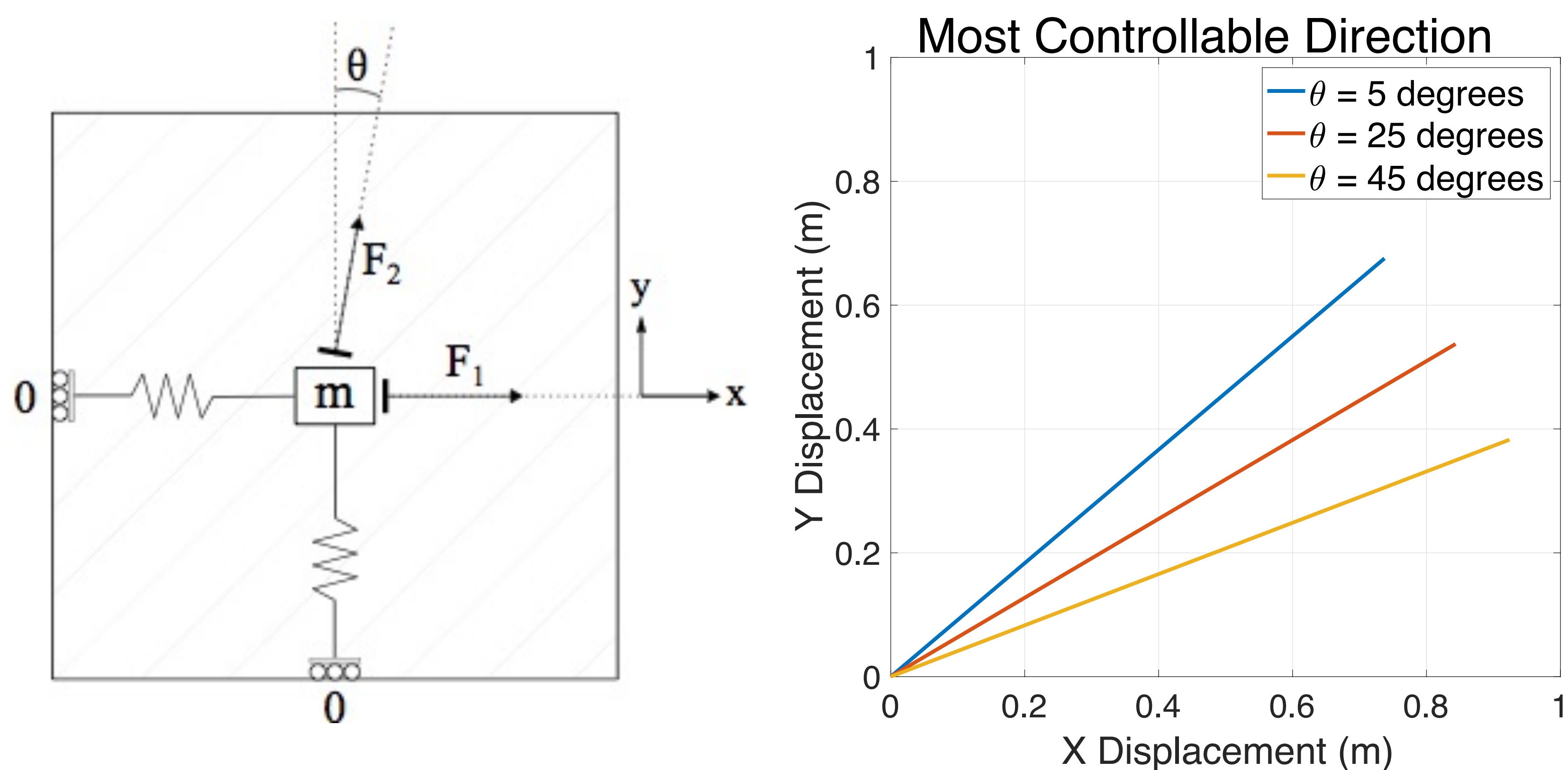
$$W_c = V \Sigma U^T = U \Sigma U,$$

where \bar{u}_1 corresponds to most controllable direction

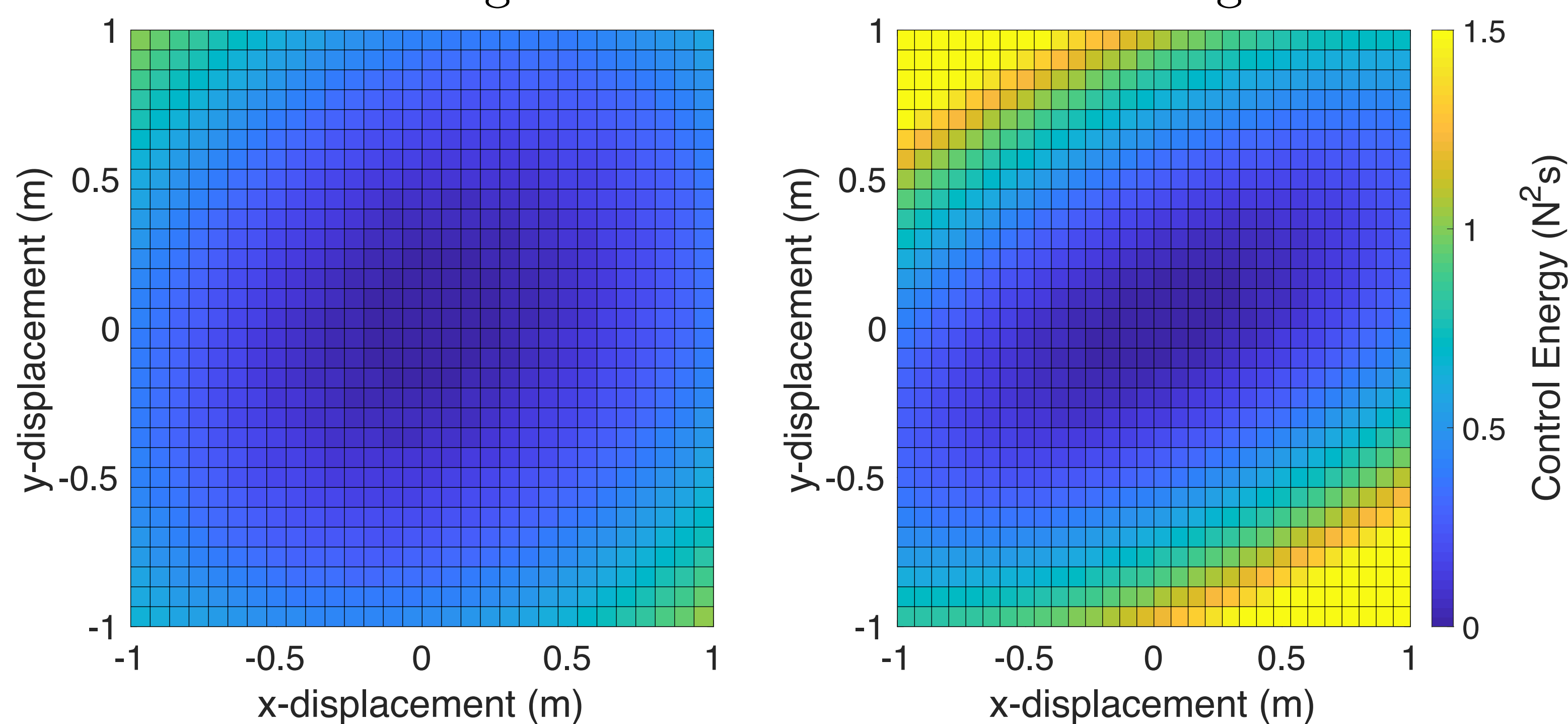


[1] Yu W, Müller K and Lemmer F 2018 LIFES50+ d4. 2: Public definition of the two LIFES50+ 10 MW floater concepts (University of Stuttgart)

A Point Mass Example



Control Energy to Return to the Origin (N²s)
 $\theta = 15$ Degrees $\theta = 45$ Degrees



Floating Offshore Wind Turbine Analysis, DTU 10MW Reference Turbine

